



## **Cambridge International Examinations**Cambridge International Advanced Level

# FURTHER MATHEMATICS 9231/11 Paper 1 MARK SCHEME Maximum Mark: 100

#### **Published**

This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began, which would have considered the acceptability of alternative answers.

Mark schemes should be read in conjunction with the question paper and the Principal Examiner Report for Teachers.

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### **Mark Scheme Notes**

Marks are of the following three types:

- M Method mark, awarded for a valid method applied to the problem. Method marks are not lost for numerical errors, algebraic slips or errors in units. However, it is not usually sufficient for a candidate just to indicate an intention of using some method or just to quote a formula; the formula or idea must be applied to the specific problem in hand, e.g. by substituting the relevant quantities into the formula. Correct application of a formula without the formula being quoted obviously earns the M mark and in some cases an M mark can be implied from a correct answer.
- A Accuracy mark, awarded for a correct answer or intermediate step correctly obtained.

  Accuracy marks cannot be given unless the associated method mark is earned (or implied).
- B Mark for a correct result or statement independent of method marks.
- When a part of a question has two or more "method" steps, the M marks are generally independent unless the scheme specifically says otherwise; and similarly when there are several B marks allocated. The notation DM or DB (or dep\*) is used to indicate that a particular M or B mark is dependent on an earlier M or B (asterisked) mark in the scheme. When two or more steps are run together by the candidate, the earlier marks are implied and full credit is given.
- The symbol 
   <sup>↑</sup> implies that the A or B mark indicated is allowed for work correctly following on from previously incorrect results. Otherwise, A or B marks are given for correct work only. A and B marks are not given for fortuitously "correct" answers or results obtained from incorrect working.
  - Note: B2 or A2 means that the candidate can earn 2 or 0.
     B2/1/0 means that the candidate can earn anything from 0 to 2.

The marks indicated in the scheme may not be subdivided. If there is genuine doubt whether a candidate has earned a mark, allow the candidate the benefit of the doubt. Unless otherwise indicated, marks once gained cannot subsequently be lost, e.g. wrong working following a correct form of answer is ignored.

- Wrong or missing units in an answer should not lead to the loss of a mark unless the scheme specifically indicates otherwise.
- For a numerical answer, allow the A or B mark if a value is obtained which is correct to 3 s.f., or which would be correct to 3 s.f. if rounded (1 d.p. in the case of an angle). As stated above, an A or B mark is not given if a correct numerical answer arises fortuitously from incorrect working. For Mechanics questions, allow A or B marks for correct answers which arise from taking *g* equal to 9.8 or 9.81 instead of 10.

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The following abbreviations may be used in a mark scheme or used on the scripts:

AEF/OE	Any Equivalent Form (of answer is equally acceptable) / Or Equivalent
AG	Answer Given on the question paper (so extra checking is needed to ensure that the detailed working leading to the result is valid)
CAO	Correct Answer Only (emphasising that no "follow through" from a previous error is allowed)
CWO	Correct Working Only – often written by a 'fortuitous' answer
ISW	Ignore Subsequent Working
SOI	Seen or implied
SR	Special Ruling (detailing the mark to be given for a specific wrong solution, or a case where some standard marking practice is to be varied in the light of a particular circumstance)

#### **Penalties**

- PA –1 This is deducted from A or B marks in the case of premature approximation. The PA –1 penalty is usually discussed at the meeting.

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1	$\frac{1}{(2r-1)(2r+1)} = \frac{1}{2} \left( \frac{1}{2r-1} - \frac{1}{2r+1} \right)$	M1A1	
	$\sum_{r=1}^{n} \frac{1}{(2r)^{2} - 1} = \frac{1}{2} \left( \left[ 1 - \frac{1}{3} \right] + \left[ \frac{1}{3} - \frac{1}{5} \right] + \dots + \left[ \frac{1}{2n - 1} - \frac{1}{2n + 1} \right] \right) = \frac{1}{2} \left( 1 - \frac{1}{2n + 1} \right)  (OE)$	M1A1	[4]
	$\frac{1}{2} \left( 1 - \frac{1}{2n+1} \right) = \frac{n}{2n+1} \Rightarrow \sum_{r=1}^{\infty} \frac{1}{\left( 2r \right)^2 - 1} = \frac{1}{2}$	B1√ <sup>^</sup>	[1]
2	$2\sum \alpha\beta = 9 - 1 \Rightarrow \sum \alpha\beta = 4$	M1A1	
	Use of, e.g.: $\sum \alpha^3 - 3\alpha\beta\gamma = \sum \alpha \left(\sum \alpha^2 - \sum \alpha\beta\right)$	M1	
	or $(\sum \alpha)^3 = \sum \alpha^3 + 3\sum \alpha \sum \alpha \beta - 3\alpha \beta \gamma$		
	Correct substitution in formula	<b>A1</b>	
	$\Rightarrow \alpha\beta\gamma = -7$	A1	
	Required cubic equation is $x^3 - 3x^2 + 4x + 7 = 0$ must see final equation	A1√	[ <u>[</u>
	ALT METHOD: $S_3 - 3S_2 + 4S_1 + 3r = 0$ M1 $3r = 30 + 3 \times 1 - 4 \times 3$ A1 $r=7$ A1		[6]

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$\mathbf{P} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}, \ \mathbf{D} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \text{soi}$	B1B1	
$\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \mathbf{D} \Longrightarrow \mathbf{A} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1} \text{ soi}$	M1	
$\mathbf{P}^{-1} = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$	M1A1	
$\mathbf{PD} = \begin{pmatrix} -1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{pmatrix} \text{ or } \mathbf{DP}^{-1} = \begin{pmatrix} -1 & 1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{pmatrix}$	M1	
$\mathbf{A} = \begin{pmatrix} -1 & 2 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix}.$	A1	[7]
ALT METHOD:		
$\mathbf{A}\mathbf{v}_1 = -\mathbf{v}_1, \mathbf{A}\mathbf{v}_2 = \mathbf{v}_2, \mathbf{A}\mathbf{v}_3 = 2\mathbf{v}_3 \mathbf{M}1, \mathbf{A}1$ Multiply out, solve each equation $\mathbf{M}1, \mathbf{A}1, \mathbf{A}1$ $\mathbf{A} = \begin{pmatrix} -1 & 2 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix} \mathbf{B}1\sqrt{1}}$		
	$\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \mathbf{D} \Rightarrow \mathbf{A} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1} \text{ soi}$ $\mathbf{P}^{-1} = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$ $\mathbf{P}\mathbf{D} = \begin{pmatrix} -1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{pmatrix} \text{ or } \mathbf{D}\mathbf{P}^{-1} = \begin{pmatrix} -1 & 1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{pmatrix}$ $\mathbf{A} = \begin{pmatrix} -1 & 2 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix}.$ ALT METHOD: $\mathbf{A}\mathbf{v}_{1} = -\mathbf{v}_{1}, \mathbf{A}\mathbf{v}_{2} = \mathbf{v}_{2}, \mathbf{A}\mathbf{v}_{3} = 2\mathbf{v}_{3}\mathbf{M}1, \mathbf{A}1$	$\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \mathbf{D} \Rightarrow \mathbf{A} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1} \text{ soi}$ $\mathbf{M}1$ $\mathbf{P}^{-1} = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$ $\mathbf{M}1\mathbf{A}1$ $\mathbf{P}\mathbf{D} = \begin{pmatrix} -1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{pmatrix} \text{ or } \mathbf{D}\mathbf{P}^{-1} = \begin{pmatrix} -1 & 1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{pmatrix}$ $\mathbf{M}1$ $\mathbf{A}1$ $1$ $\mathbf{A}1$ $$

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4	$\binom{n}{r-1} + \binom{n}{r} = \frac{n!}{(r-1)!(n-r+1)!} + \frac{n!}{r!(n-r)!} = \frac{n!}{(r-1)!(n-r)!} \left(\frac{1}{n-r+1} + \frac{1}{r}\right)$	M1	
	$= \frac{n!}{(r-1)!(n-r)!} \left( \frac{r+n-r+1}{r(n-r+1)} \right) = \frac{(n+1)!}{r!(n-r+1)!} = \binom{n+1}{r}$	A1	[2]
	$(a+x)^1 = {1 \choose 0}a + {1 \choose 1}x = a+x \Rightarrow H_1 \text{ is true.}$	B1	
	Assume $H_k$ is true,i.e. $ (a+x)^k = \binom{k}{0} a^k + \binom{k}{1} a^{k-1} x + \dots + \binom{k}{r} a^{k-r} x^r + \dots + \binom{k}{k} x^k $	B1	
	Multiplying by $(a+x)$ , the coefficient of $a^{k-r+1}x^r$ is: $\binom{k}{r-1} + \binom{k}{r} = \binom{k+1}{r}$	M1	
	$\Rightarrow$ H <sub>k+1</sub> is true.		
	Hence $H_n$ is true for all positive integers.	A1	[4]

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5 (i)	$ \begin{pmatrix} 1 & 3 & 5 & 7 \\ 2 & 8 & 7 & 9 \\ 3 & 13 & 9 & 11 \\ 6 & 24 & 21 & 27 \end{pmatrix} \Rightarrow \dots \Rightarrow \begin{pmatrix} 1 & 3 & 5 & 7 \\ 0 & 2 & -3 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}. $ $ \mathbf{r}(\mathbf{A}) = 4 - 2 = 2 $	M1A1	[3]
(ii)	Basis for range space is $\left\{ \begin{pmatrix} 1\\2\\3\\6 \end{pmatrix}, \begin{pmatrix} 3\\8\\13\\24 \end{pmatrix} \right\}$ oe	B1	[1]
(iii)	2y - 3z - 5t = 0	B1	
	Solving $\Rightarrow$ A basis for null space is $\left\{ \begin{pmatrix} -29 \\ 5 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} -19 \\ 3 \\ 2 \\ 0 \end{pmatrix} \right\}$ oe	M1 A1A1	[4]

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6	$m^2 + 7m + 10 = 0 \Rightarrow (m+2)(m+5) = 0 \Rightarrow m = -2 \text{ or } -5$ CF: $Ae^{-2t} + Be^{-5t}$	M1 A1	
	PI: $x = p \sin 2t + q \cos 2t \Rightarrow \dot{x} = 2p \cos 2t - 2q \sin 2t \Rightarrow x = -4p \sin 2t - 4q \cos 2t$	M1A1	
	Substituting: $14p+6q=0$ 6p-14q=116 Solving: $p=3$ , $q=-7 \Rightarrow x=3\sin 2t-7\cos 2t$	M1 M1A1	
	GS: $x = Ae^{-2t} + Be^{-5t} + 3\sin 2t - 7\cos 2t$	A1 <sup>∱</sup>	[8]
	For large positive values of $t \approx 3 \sin 2t - 7 \cos 2t$ .	B1√	[1]

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7 (i)	M.V. = $\frac{\left[e^{-2x}\right]_0^2}{2-0} = \frac{e^{-4}-1}{2} (=-0.491)$	M1A1	[2]
(ii)	Coordinates are $\bar{x} = \frac{\int_0^2 x e^{-2x} dx}{\int_0^2 e^{-2x} dx}$ and $\bar{y} = \frac{1}{2} \frac{\int_0^2 e^{-4x} dx}{\int_0^2 e^{-2x} dx}$	M1M1	
	$\int_{0}^{2} e^{-2x} dx = \left[ -\frac{1}{2} e^{-2x} \right]_{0}^{2} = \frac{1}{2} (1 - e^{-4}) $ (= 0.4908) (N.B. As in (i))	B1	
	$\int_{0}^{2} x e^{-2x} dx = \left[ -\frac{x e^{-2x}}{2} \right]_{0}^{2} + \int_{0}^{2} \frac{e^{-2x}}{2} dx = \left[ -\frac{x e^{-2x}}{2} - \frac{e^{-2x}}{4} \right]_{0}^{2} = -\frac{5e^{-4}}{4} + \frac{1}{4} (= 0.2271)$	M1A1	
	$\frac{1}{2} \int_{0}^{2} e^{-4x} dx = \frac{1}{2} \left[ -\frac{e^{-4x}}{4} \right]_{0}^{2} = \frac{1}{2} \left( \frac{1}{4} - \frac{e^{-8}}{4} \right)  (= 0.12495) \text{ (not straight from calculator)}$	M1A1	
	$\overline{x} = 0.463$ , $\overline{y} = 0.255$ (Final answers in algebraic form SRA1)	A1A1	[9]

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8	2x+4(xy'+y)-2yy'=0  (*) $y'=0 \Rightarrow 2x+4y=0 \Rightarrow x=-2y \text{ (AG)}$	M1A1 A1	[3]
	At stationary points $4y^2 - 8y^2 - y^2 + 20 = 0 \Rightarrow 5y^2 = 20 \Rightarrow y = \pm 2$ Coordinates of stationary points are $(4, -2)$ and $(-4, 2)$	M1A1 A1	[ع]
	From (*): $x + 2(xy' + y) - yy' = 0$		
	Differentiating: $1 + 2(xy'' + y' + y') - (yy'' + [y']^2) = 0$ (or by quotient rule)	M1A1	
	At $(4, -2)$ with $y' = 0$ : $1 + 8y'' + 2y'' = 0 \Rightarrow y'' = -\frac{1}{10} \Rightarrow$ maximum.	M1A1	
	At (-4, 2) with $y' = 0$ : $1 - 8y'' - 2y'' = 0 \Rightarrow y'' = \frac{1}{10} \Rightarrow$ minimum.	A1	[8]

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9	$\int_{0}^{\frac{\pi}{2}} x \sin x dx = \left[ -x \cos x \right]_{0}^{\frac{\pi}{2}} + \int_{0}^{\frac{\pi}{2}} \cos x dx = 0 + \left[ \sin x \right]_{0}^{\frac{\pi}{2}} = 1$	M1A1	[2]
	$I_{n} = \left[ -x^{n} \cos x \right]_{0}^{\frac{\pi}{2}} + \int_{0}^{\frac{\pi}{2}} nx^{n-1} \cos x dx$	M1A1	
	$= \left[ -x^n \cos x + nx^{n-1} \sin x \right]_0^{\frac{\pi}{2}} - \int_0^{\frac{\pi}{2}} n(n-1)x^{n-2} \sin x dx$	A1	
	$= n \left(\frac{\pi}{2}\right)^{n-1} - n(n-1)I_{n-2}$	A1	[4]
	$x = \cos^{-1} u \Rightarrow u = \cos x \Rightarrow \frac{du}{dx} = -\sin x \; ; \; u = 0 \; , 1 \Rightarrow x = \pi/2 \; , 0$	B1B1	
	$\int_{0}^{1} \left( \left[ \cos^{-1} u \right]^{3} \right) du = -\int_{\pi/2}^{0} x^{3} \sin x dx = \int_{0}^{\pi/2} x^{3} \sin x dx = I_{3}$	B1	
	$I_3 = 3\left(\frac{\pi}{2}\right)^2 - 3 \times 2 \times I_1 = \frac{3}{4}\pi^2 - 6$ (OE)	M1A1	[5]

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10	$z^{n} = \cos n\theta + i\sin n\theta$ and $z^{-n} = \cos(-n\theta) + i\sin(-n\theta) = \cos n\theta - i\sin n\theta$		
	$\Rightarrow z^n + \frac{1}{z^n} = 2\cos n\theta  \text{and}  z^n - \frac{1}{z^n} = 2i\sin n\theta . \text{ (AG)}$	M1A1	[2]
	$\left(z - \frac{1}{z}\right)^4 \left(z + \frac{1}{z}\right)^2 = \left(z - \frac{1}{z}\right)^2 \left(z^2 - \frac{1}{z^2}\right)^2 $ (Or 1st bracket expanded)	M1	
	$= \left(z^2 - 2 + \frac{1}{z^2}\right) \left(z^4 - 2 + \frac{1}{z^4}\right) $ (and 2nd bracket expanded)	M1	
	$= \left(z^6 + \frac{1}{z^6}\right) - 2\left(z^4 + \frac{1}{z^4}\right) - \left(z^2 + \frac{1}{z^2}\right) + 4  \text{(Expanded and grouped)}$	M1A1	
	$\Rightarrow 64\sin^4\theta\cos^2\theta = 2\cos 6\theta - 4\cos 4\theta - 2\cos 2\theta + 4$	M1A1	
	$\Rightarrow \sin^4\theta \cos^2\theta = \frac{1}{32} \left(\cos 6\theta - 2\cos 4\theta - \cos 2\theta + 2\right) \text{ (AG) (Uses initial result)}$	A1	[7]
	$\int_{0}^{\frac{1}{4}\pi} \sin^{4}\theta \cos^{2}\theta  d\theta = \frac{1}{32} \left[ \frac{1}{6} \sin 6\theta - \frac{1}{2} \sin 4\theta - \frac{1}{2} \sin 2\theta + 2\theta \right]_{0}^{\frac{1}{4}\pi}$	M1A1	
	$= \frac{1}{32} \left( -\frac{1}{6} - 0 - \frac{1}{2} + \frac{\pi}{2} \right) = \left( \frac{3\pi - 4}{192} \right) \text{ or } 0.0283 \text{ (3sf)}$	A1	[3]
	ALT METHOD: Expand and group each bracket separately and sub trig: M1, A1, A1 Multiply together two brackets and manipulate trig expressions M1,M1 LHS = RHS M1 A1		

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11 E	$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & -3 & -1 \\ 3 & -4 & -2 \end{vmatrix} = \begin{pmatrix} 2 \\ -1 \\ 5 \end{pmatrix}$	M1A1	
	Obtains three equations. E.g. from $\overrightarrow{OP} + \overrightarrow{PQ} = \overrightarrow{OQ}$		
	t-3s+2k = 4  -3t+4s-k = -2	M1A1	
	-3t+4s-k=-2 $-t+2s+5k=4$	WIIAI	
	Solves: $s = -1$ , $t = -1$ , $k = 1$	M1A1	
	$\mathbf{p} = 3\mathbf{i} + \mathbf{j} + 2\mathbf{k}$ and $\mathbf{q} = \mathbf{i} + 2\mathbf{j} - 3\mathbf{k}$ (Both required)	A1	[7]
	ALT METHOD: Find PQ in terms of s,t $M1$ Calculate scalar products direction vectors for $l_1$ and $l_2$ $M1,A1,A1$ Solve simultaneous equations $M1$ $A1$ p and q $A1$		[7]
	$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & -4 & -2 \\ 2 & -1 & 5 \end{vmatrix} = \begin{pmatrix} -22 \\ -19 \\ 5 \end{pmatrix}$	B1	
	$\mathbf{r} = \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix} + \lambda \begin{pmatrix} -22 \\ -19 \\ 5 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ -1 \\ 5 \end{pmatrix}$	B1B1	[3]

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Direction of $l_3$ is $\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & -4 & -2 \\ 0 & 0 & 1 \end{vmatrix} = \begin{pmatrix} -4 \\ -3 \\ 0 \end{pmatrix} \sim \begin{pmatrix} 4 \\ 3 \\ 0 \end{pmatrix}$	В1	
Normal to $\Pi$ is $\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 22 & 19 & -5 \\ 2 & -1 & 5 \end{vmatrix} = \begin{pmatrix} 90 \\ -120 \\ -60 \end{pmatrix} = \begin{pmatrix} 3 \\ -4 \\ -2 \end{pmatrix}$	M1	
Cartesian equation of $\Pi$ is $3x - 4y - 2z = 1$ (Since $P$ lies in $\Pi$ )	<b>A1</b> √^	
Vector equation of $l_3$ is $\mathbf{r} = \begin{pmatrix} -1 \\ -1 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 4 \\ 3 \\ 0 \end{pmatrix}$ (OE) (Since $z = 0$ .)	B1	[4]

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11 0	$\dot{x}^2 + \dot{y}^2 = 36t^2 + 1 - 18t^2 + 81t^4 = 1 + 18t^2 + 81t^4 = (1 + 9t^2)^2 $ (AG)	M1A1	[2]
(i)	$s = \int_{0}^{\frac{1}{\sqrt{3}}} (1+9t^{2}) dt = \left[t+3t^{3}\right]_{0}^{\frac{1}{\sqrt{3}}} = \frac{2}{\sqrt{3}}$	M1A1	[2]
(ii)	$S = 2\pi \int_{0}^{\frac{1}{\sqrt{3}}} t (1 - 3t^{2}) (1 + 9t^{2}) dt = 2\pi \int_{0}^{\frac{1}{\sqrt{3}}} (t + 6t^{3} - 27t^{5}) dt$	*M1	
	$=2\pi \left[\frac{1}{2}t^2 + \frac{3}{2}t^4 - \frac{9}{2}t^6\right]_0^{\frac{1}{\sqrt{3}}} = \frac{\pi}{3}$	DM1A1	[3]
	Substitute $t = \frac{y}{x}$ in one of the parametric equations to obtain e.g. $x = 1 - 3\frac{y^2}{x^2}$ .	M1	
	Uses $x = r\cos\theta$ and $y = r\sin\theta \Rightarrow r\cos\theta = 1 - 3\tan^2\theta \Rightarrow r = \sec\theta (1 - 3\tan^2\theta)$ .	M1A1	
	States domain for $\theta$ : $0 \le \theta \le \frac{\pi}{6}$ ,	B1	[4]
	$A = \frac{1}{2} \int_{0}^{\frac{\pi}{6}} \sec^{2}\theta \left(1 - 6\tan^{2}\theta + 9\tan^{4}\theta\right) d\theta$ $= \frac{1}{2} \left[ \tan\theta - 2\tan^{3}\theta + \frac{9}{5}\tan^{5}\theta \right]_{0}^{\frac{\pi}{6}} = \frac{4}{45} \sqrt{3}$	M1	
	$= \frac{1}{2} \left[ \tan \theta - 2 \tan^3 \theta + \frac{9}{5} \tan^5 \theta \right]_0^{\frac{\pi}{6}} = \frac{4}{45} \sqrt{3}$	A1A1	[3]